

# Bench Study \_ Elastic Supports of the Chisel Cultivator

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**Abstract.** The article discusses a comparative study of the choice of the type of racks of the working parts of a chisel-cultivator. In bench tests, each rack was fixed to a special frame; a static load was applied to them, simulating the resultant force of soil resistance. At each loading stage, movements of the toe of the paw were measured. In addition, the agro-energy performance indicators of the chisel-cultivator with various stands were studied. By results research selected spiral elastic stand .

**Key words:** working body, stand, chisel cultivator, spring-safety suspension, spiral elastic strut, static load, kinematics of the toe of the working body, stiffness of the struts, movement of the toe

**Introduction.** One of the ways to increase the efficiency and productivity, as well as the reliability of chisel implements in pre-sowing tillage, is to improve the design of their working parts. It should be noted that in the last period there have been significant changes in the energy base of agriculture, energy-rich high-speed tractors have been created and are increasingly being used . At the same time, individual agricultural implements and their working parts remained the same, this also applies to the chisel cultivator. In the cotton-growing zone, chisel cultivators are the main tools for loosening the soil after leaching and reserve irrigation. Recently, both in our country and abroad , the working parts of chisel-cultivators and other soil-cultivating machines have been equipped with spring-safety or elastic struts. According to many researchers, the use of such racks leads to a decrease in the traction resistance of the implement, provides better quality indicators of its operation, and eliminates breakdowns of the working parts [1-7].

Despite this, the working parts of cotton chisel cultivators ChKU-4 and ChKU-4A still have rigid stands. In this regard, we conducted a scientific, technical and patent review of the leading countries producing chisel guns, and based on its results, we selected the most promising options for elastic struts and suspensions (Fig. 1 and Table 1)

Table 1  
Parameters of elastic struts and spring-safety suspension

| № | Option s | Name   | Weight G, kg | Dimensions , mm _ |      |       |           |
|---|----------|--|--------------|-------------------|------|-------|-----------|
|   |          |  |              | H                 | E    | a x c | from x to |
| 1 | 1        | Spring-safety suspension of the KPE-3.8 cultivator | 27.5         | 560               | 18 0 | 55*25 | -         |
| 2 | 2        | Spiral elastic strut of the KChP-5.4 cultivator    | 16.4         | 660               | 40 0 | 30*30 | -         |
| 3 | 3        | Spiral elastic strut "VISHOM"                      | 15.4         | 630               | 27 0 | 30*30 | -         |
| 4 | 4        | Spring C-shaped stand of the KPS-4 cultivator      | 4.6          | 460               | 50   | 40*8  | -         |
| 5 | 5        | Spring S -shaped cultivator stand NZ - 9.7         | 4.1          | 300               | 26 0 | 23*9  | 45*9      |

- I. Spring-safety suspension of the cultivator KPE- 3, 8;
- II. Spiral elastic strut of the KChP-5, 4 cultivator;
- III. Spiral elastic strut of the VISHOM design;
- IV. C-shaped stand of the KPS-4 cultivator
- V. S - shaped stand of the spring cultivator NZ - 97 from the company Vader tad (Sweden).

**Materials and methods.** These stands have undergone comparative bench and laboratory field tests in order to select the most rational of them for the working parts of cotton chisel cultivators.

In bench tests, each rack was fixed to a special frame; a static load was applied to them, simulating the resultant force of soil resistance. At each loading stage, the movements of the toe of the paw (working body) were measured horizontally "e" and vertically "h" (Fig. 2).

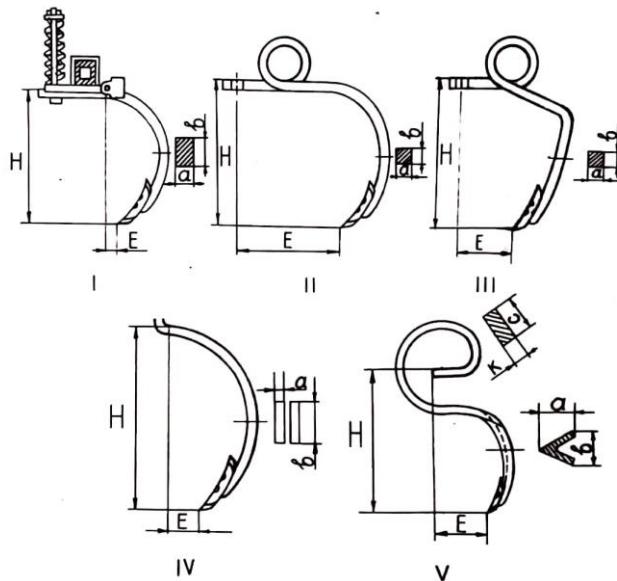


Fig. 1. Types of studied struts of the working parts of the chisel-cultivator

Based on the data obtained, the rigidity of the struts was determined and their elastic characteristics were plotted in the form of graphs expressing the horizontal dependence of the toe of the paw on the load (Fig. 3.a). For clarity, these graphs are combined with diagrams showing the kinematics of the toe of the working element (Fig. 3.b). It should be noted that in order to ensure the oscillatory process of the working body and the uniformity of the tillage depth, the rigidity of the stand should be in the range of 15-20 N/mm, and the movement of the toe of the working body in the vertical direction under the influence of the working load, which is equal to 0.8.. 1.2kN [1], should not exceed +2cm.

**Research results.** Analysis of the bench test results showed the following. Spring-safety suspension (in Fig. 3, curve I) has a two-stage characteristic. In the load range up to 1.2 kN, its rigidity decreases from 67 to 21 N/mm, and with a further increase in load to 1.6 kN, it increases to 24 N/mm. In the operating load range, the rigidity of this rack is 20-25 N/mm. With increasing paw load deepens, i.e. her toe moves up. At the maximum working load, the deepening of the paw was 15 mm, which is acceptable according to agro technical requirements [8-11].

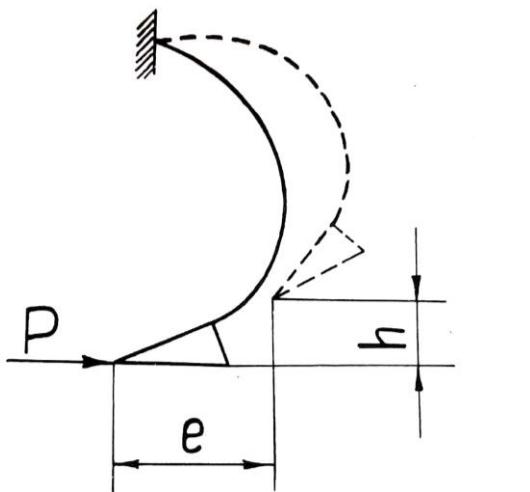


Fig. 2. Diagram for determining the movement of the toe of the working body

The spiral elastic struts of the KChP-5.4 cultivator (curve II in Fig. 3 ) and "VISKHOM" (curve III in Fig. 3 ) have a rectilinear elastic characteristic. Their longitudinal stiffness is almost the same and amounts to

15.2...17.4 and 14.3...16.7 N/mm, respectively. As the load increases, the paw deepens on both racks. However, the cultivator stand KChP-5.4 has a tine recess that is twice as large as that of the VISKHOM stand, and already at a working load of 0.8 kN it exceeds the permissible limit. At the "VISHOM" rack in the operating load range (0.8....1.2kN), the paw protrusion is 10....16 mm, which is within acceptable limits. The C-shaped rack also has a curved characteristic (curve IV in Fig. 3). In the load range up to 1 kN, its rigidity decreases from 22 to 17 N/mm. As the load increases, the paw deepens, i.e. under the influence of the working load; its toe moved downwards, this entail uneven processing depth and an increase in traction resistance.

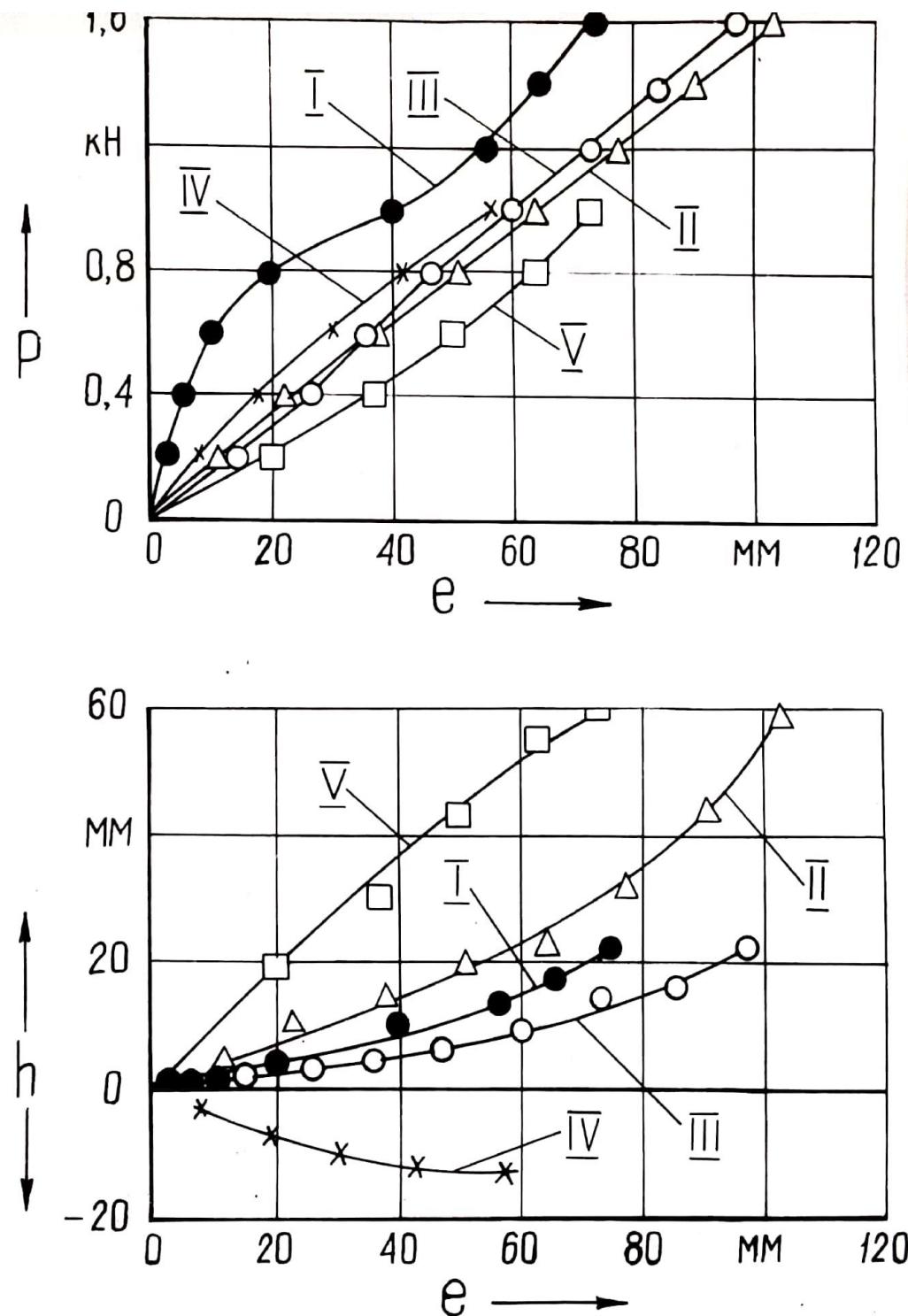


Fig. 3. Elastic characteristics of the racks (a) and kinematics of the working element (b): to the curves I ; II ; III ; IV ; V correspond to the types of racks in Fig. I

Based on this, the stand in question can also be considered unacceptable for ripening chisel cultivator paws. The S - shaped strut has a faintly expressed curvilinear characteristic (curve V in Fig. 3) and low rigidity (10...13N/mm). With increasing load, the paw intensively deepens and, throughout the entire working load range, its deepening significantly exceeds the permissible limit. Therefore, this chisel cultivator stand is not acceptable.

**Conclusions.** Thus, the research results show that the most suitable for cotton chisel-cultivator are the VISKHOM spiral elastic stand and the spring-safety suspension.

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