

On Generalized Derivations Of Jordan Algebras

Voxobov Fazliddin Faxriddinjon o'g'li
 Kokan State Pedagogical Institute

Annotation. In the present article the concept of generalized derivations of Jordan algebras is introduced and the general properties of generalized derivations are studied. In particular, invariants are constructed in Jordan algebras using generalized derivations. Also, a description, for some values of the parameters α, β, γ , of the sets of all (α, β, γ) -derivations of Jordan algebras is given.

Key words: Vector space, Jordan algebra, linear map, derivation, generalized derivation.

1-olimiting. Jordanov's algebra is - I satisfy J its conditions
 $a \cdot b = b \cdot a, a, b \in J,$

$$(a^2 \cdot b) \cdot a = a^2 \cdot (b \cdot a), a, b \in J.$$

$J \times J \rightarrow J$ – linear reflection of vector space over a field $V \ F$

The definition - differentiation of Jordan algebras (α, β, γ) can be written as follows:

2-o limiting. Let Jordanov's algebra. (J, \cdot) –

A linear operator is called $d \in \text{End}(J)$ (α, β, γ) – a differentiation if for all elements there are such , $x, y \in J, \alpha, \beta, \gamma \in \mathbf{C}$ which fulfills the following condition

$$\alpha d(x \cdot y) = \beta(d(x) \cdot y) + \gamma(x \cdot d(y)).$$

Sets of all jordan differentiations (α, β, γ) – J yx algebras denote by $\text{Der}_{(\alpha, \beta, \gamma)}(J)$. This set is determined by the following:

$$\text{Der}_{(\alpha, \beta, \gamma)}(J) = \{d \in \text{End}(J) : \alpha d(x \cdot y) = \beta(d(x) \cdot y) + \gamma(x \cdot d(y)), x, y \in J\}.$$

Where the set is a subspace of the vector space $\text{Der}_{(\alpha, \beta, \gamma)}(J) \subseteq \text{End}(J)$.

Theorem. Let be a Jordanian algebra with a unit J – ym element and $\alpha, \beta, \gamma \in \mathbf{F}$. Then the vector space has the following $\text{Der}_{(\alpha, \beta, \gamma)}(J)$ formy.

1. , $\text{Der}_{(1,1,1)}(J) = \text{Der}(J)$ where the Lie algebra of all differentiations of Jordan algebras $\text{Der}(J)$ – y ; J

2. Sets and $\text{Der}_{(1,1,0)}(J) \subseteq \text{End}(L) \text{Der}_{(1,1,0)}(J)$

it is possible to identically equalize all the idempotent elements of the Jordan algebra $\text{Id}(J)$

$$p \in \text{Id}(J), \quad d(x) = p \cdot x, \quad x \in J$$

3. $\text{Der}_{(1,1,-1)}(J) \subseteq \text{Der}_{(1,0,0)}(J) \equiv 0$.

4. $\text{Der}_{(0,1,1)}(J) \equiv 0$

5. The set can be identically equal $Der_{(0,1,-1)}(J)$ to the set $Z_o(J) = \{a \in J \mid (b \cdot a) \cdot c = b \cdot (a \cdot c), b, c \in J\}$

$$a \in Z_o(J), d(x) = a \cdot x, x \in J.$$

6. $0; Der_{(0,1,0)}(J) \equiv$

7. Esli $\delta \neq 1$, then $Der_{(\delta,1,0)}(J) \equiv 0$.

Proof. From equality $d(x \cdot y) = d(x) \cdot y, x, y \in J$ we get $d(x) = d(e) \cdot x, x \in J$. Then, since Zhordanov's algebra is commutative, J

$$d(x \cdot y) = d(e) \cdot (x \cdot y) = d(x) \cdot y = d(y) \cdot x, x, y \in J$$

and

$$d(x \cdot y) = d(x \cdot e) \cdot y = (d(e) \cdot x) \cdot y = (d(e) \cdot y) \cdot x, x, y \in J.$$

Hence $d(e)$ —the central element. As well as

$$d(e) = d(e \cdot e) = d(e) \cdot d(e),$$

i.e. the element is idempotent $d(e)$ element.

Conversely, for each central idempotent element of the Jordan algebra J

Reflection belongs to the set and $d(x) = p \cdot x, x \in J, Der_{(1,1,0)}(J)$

va therefore, the sets can be identically aligned with the multiplicity of all the idempotent elements of the Jordan algebra $Der_{(1,1,0)}(J)$

3. By definition $Der_{(1,1,-1)}(J) = \{d \in End(J) \mid d(x \cdot y) = d(x) \cdot y - x \cdot d(y), x, y \in J\}$. There is a following equality:

$$d(x) = d(e) \cdot x - d(x), x, y \in J,$$

$$d(x \cdot y) = (d(e) \cdot x - d(x)) \cdot y - x \cdot (d(e) \cdot y - d(y)) =$$

$$(d(e) \cdot x) \cdot y - d(x) \cdot y - x \cdot (d(e) \cdot y) + x \cdot d(y) =$$

$$(d(e) \cdot x) \cdot y - x \cdot (d(e) \cdot y) - d(x \cdot y), x, y \in J,$$

$$d(e) = d(e \cdot e) = d(e) \cdot e - e \cdot d(e) = 0.$$

Hence

$$d(x \cdot y) = -d(x \cdot y) = 0, x, y \in J$$

and

$$d(e \cdot x) = -d(e \cdot x) = d(x) = 0, x \in J.$$

From the Last Equality $Der_{(1,1,-1)}(J) \equiv 0$.

4. By definition, the set is defined in the following $Der_{(0,1,1)}(J)$ way:

$$Der_{(0,1,1)}(J) = \{d \in End(J) \mid d(x) \cdot y = -x \cdot d(y), x, y \in J\}.$$

Then $d(e) \cdot x = -e \cdot d(x) = -d(x)$, $x \in J$, $d(e) \cdot e = -e \cdot d(e) = 0$

Hence

$$d(x) = e \cdot d(x) = -d(e) \cdot x = 0, \quad x \in J.$$

So, $Der_{(0,1,1)}(J) \equiv 0$.

5. As in the previous case, for the set you can get equals $Der_{(0,1,-1)}(J) = \{d \in \text{End}(J) \mid d(x) \cdot y = x \cdot d(y), x, y \in J\}$

$$d(e) \cdot x = e \cdot d(x) = d(x), \quad x \in J,$$

$$d(x) \cdot y = (d(e) \cdot x) \cdot y = (x \cdot d(e)) \cdot y = x \cdot d(y) = x \cdot (d(e) \cdot y), x, y \in J.$$

Now from the set

$$Z_o(J) = \{a \in J \mid (b \cdot a) \cdot c = b \cdot (a \cdot c), b, c \in J\}$$

let's take arbitrarily element $a \in Z_o(J)$. Let's show that reflection $d(x) = a \cdot x$, $x \in J$.

Belongs to the set $Der_{(0,1,-1)}(J)$.

$$d(x) \cdot y = (a \cdot x) \cdot y = (x \cdot a) \cdot y = x \cdot (a \cdot y) = x \cdot d(y), \quad x, y \in J.$$

6. By definition, a set is defined by following $Der_{(0,1,0)}(J)$ it:

$$Der_{(0,1,0)}(J) = \{d \in \text{End}(J) \mid d(x) \cdot y = 0, x, y \in J\}.$$

There is a following equality:

$$d(x) = d(x) \cdot e = 0, \quad d(e) = d(e) \cdot e = 0, \quad x \in J.$$

Hence $Der_{(0,1,0)}(J) \equiv 0$.

7. And at the end, of the set

$$Der_{(\delta,1,0)}(J) = \{d \in \text{End}(J) \mid \delta d(x \cdot y) = d(x) \cdot y, x, y \in J\}$$

you can get equality

$$\delta d(x) = \delta d(x \cdot e) = d(x) \cdot e = d(x), \quad x \in J$$

$$\delta d(x) = d(x), \quad (\delta - 1)d(x) = 0, \delta \neq 1, d(x) = 0 \quad x \in J.$$

Since

$$0 = (\delta - 1)^{-1} 0 = (\delta - 1)^{-1} (\delta - 1) d(x) = d(x).$$

So, $Der_{(\delta,1,0)}(J) \equiv 0$.

References:

1. Leger G., Luks E. Generalized Derivations of Lie algebras, J. Algebra, 2000, 228,165-203.
2. Hartwig J., Larsson D., Silvestrov S. Deformation of Lie algebras using σ -derivation. Journal of algebra, 2006, 38 (2) 109-138. (σ, τ)
3. Hrivnak J. Invariants of Lie algebras. PhD Thesis, Faculty of Nuclear Science and Physical Engineering, Czech Technical University, Prague, 2007.

4. Novotny P., Hrivnak J. On -derivation of Lie algebras and corresponding invariant functions. *J. Geom. Phys.*, 2008, 58, 208-217. (α, β, γ)
5. Rakhimov I. S., Said Husain Sh. K., Abdulkadir A. On Generalized derivations of finite dimensional associative algebras. *FEIIC International journal of Engineering and Technology*, 2016, 13 (2) 121-126.
6. Fiidow M.A., Rakhimov I.S., Said Husain Sh.K., Basri W. -Derivations of diassociative algebras. *Malaysian Journal Of Mathematical sciences*, 2016, 10101-126. (α, β, γ)
7. McCrimmon K.A. *A taste of Jordan algebras*. Springer, New York, Berlin, Heidelberg, Hong Kong, London, Milan, Paris, Tokyo, 2004, pp. 562.
8. Hanche-Olсен H., Störmer E. *Jordan operator algebras*. Boston etc: Pitman Publ. Inc., 1984, pp. 183.
9. Mamazhonov, M., & Shermatova, K. M. (2017). ON A BOUNDARY-VALUE PROBLEM FOR A THIRD-ORDER PARABOLIC-HYPERBOLIC EQUATION IN A CONCAVE HEXAGONAL DOMAIN. *Bulletin KRASEC. Physical and Mathematical Sciences*, 16(1), 11-16.
10. Mamajonov, M., & Shermatova, Kh. A. (2017). On one boundary point for a third-order equation of paraboloid-hyperbolic type in a concave hexagonal region. *Vestnik KRAUNTS. Physical and Mathematical Sciences*, (1 (17), 14-21.
11. Akbarov, U. Y., and F. B. Badalov. "Eshmatov X. Stability of viscoelastic rods under dynamic loading." *Prikl. mech. i tech. phys.* 4 (1992): 20-22.
12. Mamazhonov, M., and Kh B. Mamadaliyeva. "STATEMENT AND STUDY OF SOME BOUNDARY VALUE PROBLEMS FOR THIRD ORDER PARABOLIC-HYPERBOLIC EQUATION OF TYPE $\partial(Lu)/\partial x = 0$ IN A PENTAGONAL DOMAIN." *Bulletin KRASEC. Physical and Mathematical Sciences* 12.1 (2016): 27-34.
13. Abdikarimov, Rustamxon A., Mukhsin M. Mansurov, and Ummatali Y. Akbarov. "Numerical study of flutter of a viscoelastic rigidly pinched rod taking into account physical and aerodynamic nonlinearities." *Vestnik RSUH. Series: Informatics. Information Security. Mathematics* 3 (2019): 94-107.
14. Abdikarimov, Rustamxon A., Mukhsin M. Mansurov, and Ummatali Y. Akbarov. "Numerical study of a flutter of a viscoelastic rigidly clamped rod with regard for the physical and aerodynamic nonlinearities." *BECTHIK PITVY* 3 (2019): 95.
15. Abdikarimov, Rustamxon A., Mukhsin M. Mansurov, and Ummatali Y. Akbarov. "Numerical study of a flutter of a viscoelastic rigidly clamped rod with regard for the physical and aerodynamic nonlinearities." *BECTHIK PITVY* 3 (2019): 95.
16. Formanov, Sh K., and Sh Jurayev. "On Transient Phenomena in Branching Random Processes with Discrete Time." *Lobachevskii Journal of Mathematics* 42.12 (2021): 2777-2784.
17. Khusanbayev, Ya. M., and H. Q. Zhumakulov. "On the convergence of almost critical branching processes with immigration to a deterministic process." *O 'ZBEKISTON MATEMATIKA JURNALI* (2017): 142.
18. Mamazhanov M., Shermatova Kh.M., Mamadaliyeva Kh.B. On one boundary problem for the third-order equation of the paraboloid-hyperbolic type in the concave six-tumor region. *Actual scientific research in the modern world. ISCIENCE. IN. UA, Pereyaslav-Khmel'nitsky*, 2017, vol.2(22), pp. 148-151.
19. Mamajonov, M., and Khosiyatkhon Botirovna Mamadaliyeva. "Formulation and study of some boundary value problems for a third-order equation of the paraboloid-hyperbolic type of the form $\partial\partial x(Lu)=0$ in the pentagonal region." *Physical and Mathematical Sciences* 1 (12 (2016): 32-40.
20. Abdikarimov, Rustamxon A., Mukhsin M. Mansurov, and Ummatali Y. Akbarov. "Numerical study of a flutter of a viscoelastic rigidly clamped rod with regard for the physical and aerodynamic nonlinearities." *BECTHIK PITVY* 3 (2019): 95.